## <span id="page-0-0"></span>GROWTH CONDITIONS TO ENSURE INPUT-TO-STATE STABILITY OF TIME-DELAY SYSTEMS WITH POINT-WISE **DISSIPATION**

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A **time-delay system** (TDS) is a system modeled by:

<span id="page-1-0"></span>
$$
\dot{x}(t) = f(x_t, u(t)).\tag{1}
$$

 $u(t) \in \mathbb{R}^m$  is the input

 $x_t: [-\Delta, 0] \to \mathbb{R}^n$  is the solution's history defined by  $x_t(s) = x(t+s)$  for all  $s \in [-\Delta, 0],$ 



∆ is the maximum delay and we assume that *f* is Lipschitz on bounded set in what follows.

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### Comparision functions

- <sup>1</sup> Class *K*<sup>∞</sup> function: zero at zero, continuous, increasing and unbounded.
- 2 Class  $\mathcal{K} \mathcal{L}$  function :  $\beta : \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ 
	- $\theta$   $\beta(\cdot,t)$  is zero at zero, continuous and increasing
	- $\theta$   $\beta(s, \cdot)$  is continuous, decreasing and vanishing at infinity.



Figure: Class *K*<sup>∞</sup> and *K L* functions.

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TDS [\(1\)](#page-1-0) is said to be **input-to-state stable (ISS)** if there exist  $\beta \in \mathcal{KL}$  and  $\mu \in \mathcal{K}_{\infty}$ such that, for all  $x_0 \in C([-\Delta, 0], \mathbb{R}^n)$  and all  $u \in L_{loc}^{\infty}(\mathbb{R}^+, \mathbb{R}^m)$ ,

 $|x(t, x_0, u)| \leq \beta(||x_0||, t) + \mu(||u_{[0,t]}||), \ \forall t \geq 0.$  (2)



If β(*s*,*t*) = *kse*−λ*<sup>t</sup>* , the TDS [\(1\)](#page-1-0) is said to be **exponentially input-to-state stable (exp-ISS)**.

A functional *V* : *C*([−∆,0],R *n* ) → R≥<sup>0</sup> is said to be a **Lyapunov-Krasovskii functional candidate (LKF)** if it is **Lipschitz on bounded sets** and there exist  $\underline{\alpha}, \overline{\alpha} \in \mathcal{K}_{\infty}$  such that, for all  $t \geq 0$ 

<span id="page-4-0"></span>
$$
\underline{\alpha}(|x(t)|) \le V(x_t) \le \overline{\alpha}(\|x_t\|). \tag{3}
$$

 $|x(t)|$  is a  $\mathbb{R}^n$  norm which differs from  $||x_t|| := \sup |x_t(\tau)|$ .  $\tau \in [-\Delta, 0]$ 

For TDS [\(1\)](#page-1-0), an LKF *V* is said to be

**1** an ISS LKF with LKF-wise dissipation if there exist  $\alpha, \gamma \in \mathcal{K}_{\infty}$  such that

<span id="page-5-0"></span>
$$
D^{+}V \leq -\alpha(V(x_t)) + \gamma(|u(t)|), \qquad (4)
$$

2 an ISS LKF with point-wise dissipation if there exist  $\alpha, \gamma \in \mathcal{K}_{\infty}$  such that

$$
D^{+}V \leq -\alpha(|x(t)|) + \gamma(|u(t)|). \tag{5}
$$

<span id="page-5-1"></span>4 D.K

 $D^+V$  is the Driver's derivative of the functional  $V$  along the solution of [\(1\)](#page-1-0).

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➤ From [\(3\)](#page-4-0), the following implication holds:

 $(4) \Rightarrow (5)$  $(4) \Rightarrow (5)$  $(4) \Rightarrow (5)$ 

 $\blacktriangleright$  The dissipation rate  $\alpha$  involves  $|x(t)|$  in [\(5\)](#page-5-1) (so easier) and not the LKF V itself as in [\(4\)](#page-5-0).

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Theorem 5

*TDS* [\(1\)](#page-1-0) *is ISS if and only if it admits an ISS LKF with LKF-wise dissipation.*

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Consider the LKF

$$
V(x_t) = V_1(x(t)) + \int_{-\Delta}^{0} V_2(x_t(s))ds,
$$
 (6)

Usually, according to the expression of  $f$ , the derivative of  $V$  can easily look like

<span id="page-8-0"></span>
$$
D^+V \leq -\alpha(|x(t)|) + \gamma(|u(t)|).
$$

By adding *kecs* in the kernel of integral part of [\(6\)](#page-8-0), we have

$$
W(x_t) = V_1(x(t)) + \int_{-\Delta}^0 k e^{cs} V_2(x_t(s)) ds,
$$

and with  $k > 1$ 

$$
D^{+}W \leq -\alpha(|x(t)|)-(1-k)V_{2}(x(t))-kc\int_{-\Delta}^{0}ke^{cs}V_{2}(x_{t}(s))ds+\gamma(|u(t)|).
$$

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[\[Loko et al., 2024\]](#page-16-1)(CDC)

Proposition 1

<span id="page-9-0"></span>*If there exists a constant p* > 0 *such that*

 $\alpha(|x(t)|) > pV_2(x(t)),$ 

*then* [\(9\)](#page-8-1) *is an ISS LKF with LKF-wise dissipation and the TDS* [\(1\)](#page-1-0) *is ISS.*

Proposition [1](#page-9-0) extends the result given in [\[Orłowski et al., 2022,](#page-16-2) Lemma 1] to non necessarly quadratic LKFs.

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### When the "exponential trick" does not work

#### Consider the following **1D** TDS

<span id="page-10-0"></span>
$$
\dot{x}(t) = -x(t) - \frac{x(t)}{1 + x(t)^2} + \frac{x(t-1)^4}{1 + |x(t)|^3} + \frac{u(t)}{1 + x(t)^2},\tag{7}
$$

and the LKFs:

$$
V(x_t) := \frac{1}{4}x(t)^4 + \int_{-1}^0 x_t(s)^4 ds,
$$
  
\n
$$
W(x_t) := V_1(x(t)) + \int_{-\Delta}^0 k e^{cs} V_2(x_t(s)) ds.
$$

[\[Loko et al., 2024\]](#page-16-1)(CDC)

### Proposition 2



- <sup>2</sup> *V is an ISS LKF with point-wise dissipation for* [\(7\)](#page-10-0)
- <sup>3</sup> *Given any k*, *c* > 0, *W is not an LKF with LKF-wise dissipation.*

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[\[Chaillet et al., 2017\]](#page-16-3)

### Conjecture 1

*Assume that there exist an LKF V with point-wise dissipation meaning* [\(5\)](#page-5-1) *holds. Then the system* [\(1\)](#page-1-0) *is ISS.*

In response,

- **1** [\[Chaillet et al., 2017\]](#page-16-3) provides a sufficient condition on the growth of the vector field of TDS.
- 2 [\[Chaillet et al., 2023\]](#page-16-4) provides some growth conditions on the LKF to ensure exp-ISS.

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[\[Loko et al., 2024\]](#page-16-1)(CDC)

### Theorem 6

<span id="page-12-3"></span>*Assume that there exists a LKF V which dissipates point-wisely as follow,*

$$
D^{+}V \leq -\alpha(Q(x(t))) + \gamma(|u(t)|). \tag{8}
$$

*Assume that*

<span id="page-12-1"></span>
$$
\dot{Q}(x(t)) \le \sigma(||Q||) + \gamma(|u(t)|). \tag{9}
$$

*Then, if*

<span id="page-12-0"></span>
$$
\liminf_{r \to +\infty} \frac{\alpha(r)}{\sigma(re^{2\Delta})} > 0,
$$
\n(10)

<span id="page-12-2"></span>4 0 8 4

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*the system* [\(1\)](#page-1-0) *is ISS.*

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- ➤ [\(8\)](#page-12-0) shows the point-wise dissipation of *V*
- $\triangleright$  [\(9\)](#page-12-1) presents the growth of the function *O* along the solution of the system
- $\blacktriangleright$  [\(10\)](#page-12-2) requires the growth on *Q* to be smaller than the dissipation rate  $\alpha$  (it is the main requirement)
- ➤ Theorem [6](#page-12-3) generalizes [\[Chaillet et al., 2023,](#page-16-4) Theorem 3]
- ➤ Theorem [6](#page-12-3) covers a class of TDS that cannot be covered by [\[Chaillet et al., 2017,](#page-16-3) Theorem 8].
- ➤ The proof of Theorem [6](#page-12-3) is based on [\[Karafyllis and Jiang, 2011,](#page-16-5) Lemma 6.7]
- **1** The principle of adding exponential term in relaxed LKFs to make them strict, does not systematically work even for 1*D* TDS.
- 2 Growth condition is proposed to conclude ISS with relaxed LKF.
- **3** The proposed condition turns out to extend the existing ones.
- <sup>4</sup> The conjecture is still an open question.

For those who are intersted, I also get some other works:

<sup>1</sup> E. Loko, A. Chaillet, I. Karafyllis (2024). Bulding coercive Lyapunov-Krasovskii functional based on Razumikhin and Halanay approaches. International Journal of Robust and Nonlinear Control.

<sup>2</sup> E. Loko, A. Hayat (2024). Fredholm backstepping for general spectral operators. In process

# Thank you for your attention!

<span id="page-16-4"></span>Chaillet, A., Karafyllis, I., Pepe, P., and Wang, Y. (2023).

Growth conditions for global exponential stability and exp-ISS of time-delay systems under point-wise dissipation.

*Systems & Control Letters*, 178:105570.

<span id="page-16-3"></span>

<span id="page-16-5"></span>晶

Chaillet, A., Pepe, P., Mason, P., and Chitour, Y. (2017). Is a point-wise dissipation rate enough to show ISS for time-delay systems? *IFAC-PapersOnLine*, 50(1):14356–14361.

Karafyllis, I. and Jiang, Z.-P. (2011). *Stability and stabilization of nonlinear systems*. Springer Science & Business Media.

<span id="page-16-0"></span>Karafyllis, I., Pepe, P., and Jiang, Z.-P. (2008).

Input-to-output stability for systems described by retarded functional differential equations.

*European Journal of Control*, 14(6):539–555.

<span id="page-16-1"></span>

Loko, E., Chaillet, A., Wang, Y., Karafyllis, I., and Pepe, P. (2024).

Growth conditions to ensure input-to-state stability of time-delay systems under point-wise dissipation. In process.

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Adaptive control of Lipschitz time-delay systems by sigma modification with application to neuronal population dynamics.

*Systems & Control Letters*, 159:105082.

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