

About the dynamics of the Landau-Lifshitz equation

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Introduction

The Landau-Lifshitz equation

$$\partial_t m + m \times \left(\Delta m - J(m) \right) = 0,$$

describes an Hamiltonian dynamics for the magnetization

$$m = (m_1, m_2, m_3) : \mathbb{R}^N \times \mathbb{R} \rightarrow \mathbb{S}^2,$$

in a ferromagnetic material (Landau and Lifshitz [35]). In this equation, the diagonal matrix

$$J = \begin{pmatrix} j + \lambda_1 & 0 & 0 \\ 0 & j & 0 \\ 0 & 0 & j + \lambda_3 \end{pmatrix},$$

gives account of the anisotropy of the material.

In dimension $N = 1$, the Landau-Lifshitz equation is integrable by means of the inverse scattering method (Sklyanin [79]) :

- this equation owns a form of universality (see e.g. Faddeev and Takhtajan [87]) in the sense that it contains other integrable equations in suitable asymptotic regimes.

- its long-time dynamics is governed by the propagation of a train of solitons plus a dispersive part.

I. Asymptotic models in higher dimensions

Deriving well-known nonlinear dispersive models from the Landau-Lifshitz equation remains possible in **any higher dimensions**. A typical example is given by the **Sine-Gordon regime**.

This regime describes the dynamics of a biaxial material in an **uniaxial regime** with **strong planar anisotropy**. The numbers λ_1 and λ_3 are given by

$$\lambda_1 = \sigma\varepsilon \quad \text{and} \quad \lambda_3 = \frac{1}{\varepsilon},$$

where $\varepsilon > 0$ is a **small parameter** and $\sigma > 0$ is a **fixed constant**.

Its derivation relies on an **hydrodynamical formulation**. When the map $\check{m} = m_1 + im_2$ does not vanish, it may be lifted as

$$\check{m} = \sqrt{1 - m_3^2} (\sin(\phi) + i \cos(\phi)).$$

The **hydrodynamical variables**

$$(\phi, u = m_3),$$

satisfy the **hydrodynamical Landau-Lifshitz equation**

$$\begin{cases} \partial_t \phi = -\operatorname{div}\left(\frac{\nabla u}{1-u^2}\right) + \frac{u|\nabla u|^2}{(1-u^2)^2} - u|\nabla \phi|^2 + u(\lambda_3 - \lambda_1 \sin^2(\phi)), \\ \partial_t u = \operatorname{div}((1-u^2)\nabla \phi) - \frac{\lambda_1}{2}(1-u^2)\sin(2\phi). \end{cases}$$

The long-wave change of variables

$$\Phi_\varepsilon(x, t) = \phi\left(\frac{x}{\sqrt{\varepsilon}}, t\right) \text{ and } U_\varepsilon(x, t) = \frac{1}{\varepsilon}u\left(\frac{x}{\sqrt{\varepsilon}}, t\right),$$

leads to the system

$$\begin{cases} \partial_t \Phi_\varepsilon = U_\varepsilon \left(1 - \varepsilon^2 (\sigma \sin^2(\Phi_\varepsilon) + |\nabla \Phi_\varepsilon|^2) \right) \\ \quad - \operatorname{div} \left(\frac{\varepsilon^2 \nabla U_\varepsilon}{1 - \varepsilon^2 U_\varepsilon^2} \right) + \frac{\varepsilon^4 U_\varepsilon |\nabla U_\varepsilon|^2}{(1 - \varepsilon^2 U_\varepsilon^2)^2}, \\ \partial_t U_\varepsilon = \operatorname{div} \left((1 - \varepsilon^2 U_\varepsilon^2) \nabla \Phi_\varepsilon \right) - \frac{\sigma}{2} (1 - \varepsilon^2 U_\varepsilon^2) \sin(2\Phi_\varepsilon). \end{cases} \quad (\text{HLL}_\varepsilon)$$

When $\varepsilon \rightarrow 0$, the limit function Φ satisfies the Sine-Gordon equation

$$\partial_{tt} \Phi - \Delta \Phi + \frac{\sigma}{2} \sin(2\Phi) = 0. \quad (\text{SG})$$

Theorem (de Laire and G. [17]). Let $k > N/2$ and $0 < \varepsilon < 1$. Consider an initial datum (Φ_0, U_0) such that the quantity

$$\kappa_0 = \|\nabla\Phi_0\|_{H^{k+3}} + \varepsilon\|\nabla U_0\|_{H^{k+3}} + \|\sin(\Phi_0)\|_{H^{k+3}} + \|U_0\|_{H^{k+3}},$$

satisfies the condition $C\varepsilon\kappa_0 \leq 1$ for a positive number C . There exists a number

$$T_\varepsilon \geq \frac{1}{C\kappa_0^2},$$

such that the corresponding solutions $(\Phi_\varepsilon, U_\varepsilon)$ to (HLL_ε) , and (Φ, U) to (SG) , satisfy

$$\begin{aligned} & \|\sin(\Phi_\varepsilon(\cdot, t) - \Phi(\cdot, t))\|_{L^2} + \|\nabla\Phi_\varepsilon(\cdot, t) - \nabla\Phi(\cdot, t)\|_{H^{k-1}} \\ & + \|U_\varepsilon(\cdot, t) - U(\cdot, t)\|_{H^k} \leq C\varepsilon^2\kappa_0(1 + \kappa_0)^3 e^{C(1+\kappa_0)^2 t}, \end{aligned}$$

for any $0 \leq t \leq T_\varepsilon$.

(see also Shatah and Zeng [06], Chiron [14], Germain and Rousset [16], and de Laire and G. [21])

II. Stability of solitons for the Landau-Lifshitz equation with an easy-plane anisotropy

1. Link with the Gross-Pitaevskii equation

For $\lambda_1 = 0$ and $\lambda_3 = 1$, the Landau-Lifshitz equation with an easy-plane anisotropy writes as

$$\partial_t m + m \times (\Delta m - m_3 e_3) = 0,$$

with $e_3 = (0, 0, 1)$.

When the map $\tilde{m} := m_1 + im_2$ is lifted as $\tilde{m} = \sqrt{1 - m_3^2} e^{i\varphi}$, the variables $v := m_3$ and $w := \nabla\varphi$ solve the hydrodynamical system

$$\begin{cases} \partial_t v = -\operatorname{div}((1 - v^2)w), \\ \partial_t w = -\nabla \left(v - v|w|^2 - \frac{\Delta v}{1 - v^2} - \frac{v|\nabla v|^2}{(1 - v^2)^2} \right). \end{cases} \quad (\text{HLL})$$

This system is **very similar** to the one corresponding to the **Gross-Pitaevskii equation**

$$i\partial_t\psi + \Delta\psi + \psi(1 - |\psi|^2) = 0,$$

given for a function $\psi : \mathbb{R}^N \times \mathbb{R} \rightarrow \mathbb{C}$.

When this function is indeed lifted as $\psi := \sqrt{\rho} e^{i\varphi}$, the variables $\eta := 1 - \rho$ and $v := -\nabla\varphi$ solve the **hydrodynamical Gross-Pitaevskii equation**

$$\begin{cases} \partial_t\eta = -2\operatorname{div}((1 - \eta)v), \\ \partial_tv = -\nabla\left(\eta - |v|^2 - \frac{\Delta\eta}{2(1-\eta)} - \frac{|\nabla\eta|^2}{4(1-\eta)^2}\right). \end{cases}$$

2. Travelling-wave solutions

Travelling waves are special solutions of the form

$$m(x, t) = m_c(x_1 - ct, \dots, x_N).$$

Their profile m_c is solution to the nonlinear elliptic equation

$$\Delta m_c + (|\nabla m_c|^2 + [m_c]_3^2) m_c - [m_c]_3 e_3 + c m_c \times \partial_1 m_c = 0.$$

In dimension $N = 1$, (non-constant) travelling waves are called **dark solitons**. For any speed $|c| < 1$, there exists a **unique soliton** (up to the geometric invariances), whose expression is **explicit**.

When $c \neq 0$, the soliton m_c can be identified in the hydrodynamical formulation with the pair

$$\mathbf{v}_c(x) := \left(v_c(x) = \frac{\sqrt{1-c^2}}{\cosh(\sqrt{1-c^2}x)}, w_c(x) = \frac{cv_c(x)}{1-v_c(x)^2} \right).$$

A train of solitons is then defined as a perturbation of a sum of solitons

$$S_{\mathbf{c}, \mathbf{a}, \mathbf{s}}(x) := \sum_{j=1}^N s_j \mathbf{v}_{c_j}(x - a_j),$$

for parameters $\mathbf{a} \in \mathbb{R}^N$, $\mathbf{c} \in (-1, 1)^N$ and $\mathbf{s} \in \{\pm 1\}^N$.

3. Asymptotic stability of well-prepared trains of solitons

Theorem (Bahri [18]). Let $\mathfrak{s}_0 \in \{\pm 1\}^N$ and $\mathfrak{c}_0 \in (-1, 1)^N$ with

$$[\mathfrak{c}_0]_1 < \cdots < 0 < \cdots < [\mathfrak{c}_0]_N.$$

There exist two numbers $\alpha_* > 0$ and $L_* > 0$, such that, if an initial datum $\mathfrak{v}_0 = (v_0, w_0) \in H^1(\mathbb{R}) \times L^2(\mathbb{R})$ satisfies

$$\left\| \mathfrak{v}_0 - S_{\mathfrak{c}_0, \mathfrak{a}_0, \mathfrak{s}_0} \right\|_{H^1 \times L^2} = \alpha_0 < \alpha_*,$$

for positions $\mathfrak{a}_0 \in \mathbb{R}^N$ such that

$$\min_{1 \leq k \leq N-1} ([\mathfrak{a}_0]_{k+1} - [\mathfrak{a}_0]_k) = L_0 > L_*,$$

then there exist *positions* $a_k \in C^1(\mathbb{R}_+, \mathbb{R})$, with $a_k(0) = [a_0]_k$,
and *speeds* $\sigma_k \in (-1, 1)$, with $\sigma_k \neq 0$, and,

$$a'_k(t) \xrightarrow[t \rightarrow +\infty]{} \sigma_k,$$

such that the *unique solution* \mathbf{v} of (HLL) with initial datum \mathbf{v}_0
satisfies

$$\mathbf{v}(\cdot + a_k(t), t) \xrightarrow[t \rightarrow +\infty]{} [s_0]_k \mathbf{v}_{\sigma_k} \quad \text{in } H^1(\mathbb{R}) \times L^2(\mathbb{R}),$$

for all $1 \leq k \leq N$.

(See also Martel, Merle and Tsai [02], Bethuel, G. and Smets [14, 14], G. and Smets [15], de Laire and G. [15], Bahri [16]).

4. *In higher dimensions*

In dimensions $N = 2$ and $N = 3$, Papanicolaou and Spathis [99] numerically exhibited a branch of travelling waves with speeds $|c| < 1$.

Lin and Wei [10] proved the existence of small speed travelling waves in dimension $N = 2$.

There are much more theoretical results concerning the existence and orbital stability of branches of travelling waves for the Gross-Pitaevskii equation.

(See e.g. Jones, Putterman and Roberts [82, 86], Bethuel, G. and Saut [09], Maris [13], Chiron and Pacherie [21, 23, 23], ...).

In order to improve the dynamical description of the Landau-Lifshitz equation, it is interesting to investigate numerically :

- the existence of multiple branches of travelling waves in \mathbb{R}^2 or in \mathbb{R}^3 (in the spirit of Chiron and Scheid [16, 18]),
- the dynamical interactions between travelling waves in \mathbb{R}^2 or in \mathbb{R}^3 (in the spirit of the description of the vortex motion for the Gross-Pitaevskii equation).

Thank you very much !