

Estimations d'énergie discrètes pour un modèle hyperbolique d'équations dispersives

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Collaboration with the SHOM (*Service Hydrographique et Océanographie de la Marine*).



Tolosa : Open source simulation platform for free-surface models, applications in coastal and large-scale oceanography (Shallow Water, multilayer SW and dispersive models).

Contributors :

- ▷ **R. Baraille, M. Ciavaldini, F. Couderc, P. Noble, J.P. Vila** - Toulouse
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- ▷ **F. Marche** - Montpellier
- ▷ **M. Kazakova, Y. C. Hung** - Chambéry
- ▷ **G.L. Richard** - Grenoble
- ▷ **V. Duchêne** - Rennes

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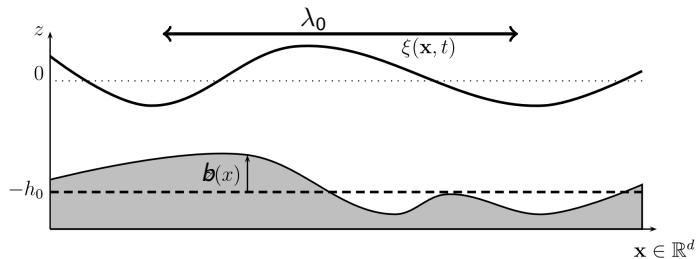
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On dispersive models



Free surface Euler equations

$$\begin{aligned}\nabla \cdot \mathbf{v} &= 0, \\ \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} &= -\nabla P.\end{aligned}$$

$$\mathbf{v} = \mathbf{v}(\mathbf{x}, z, t) \in \mathbb{R}^{d+1} \times \mathbb{R}^+.$$

$$\Omega_t = \{(\mathbf{x}, z) \in \mathbb{R}^{d+1}, -h_0 + b(\mathbf{x}) < z < \xi(\mathbf{x}, t)\}.$$

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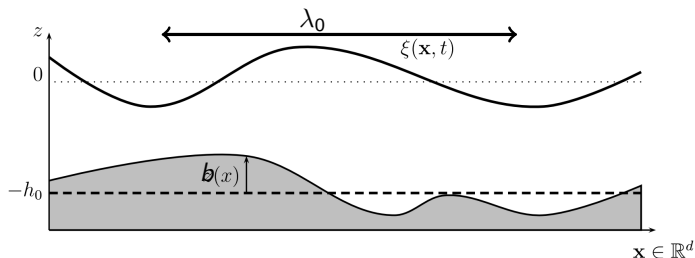
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Depth-averaging

Integration along the vertical coordinate + BC :

$$\mathbf{u}(\mathbf{x}, t) = \frac{1}{h} \int_{z(\mathbf{x})}^{\xi(\mathbf{x}, t)} \mathbf{v}_h(\mathbf{x}, z, t) dz .$$

- ▶ $\mathcal{O}(1)$: Shallow Water
- ▶ $\mathcal{O}(\mu)$: Boussinesq, Serre-Green-Naghdi, ...

$$\mu = \left(\frac{h_0}{\lambda_0} \right)^2 \ll 1$$

▷ D. Lannes, *The Water Waves problem : mathematical analysis and asymptotics*, 2013.

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Resulting equations

Shallow Water and SGN equations

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t hu + \partial_x\left(hu^2 + \frac{1}{2}gh^2 + \underbrace{\frac{1}{3}h^2\ddot{h} + \Pi}_{\mathcal{O}(\mu)}\right) = -gh\partial_x b - \underbrace{f}_{\mathcal{O}(\mu)}. \end{cases}$$

► Notations

$$\dot{h} = \frac{Dh}{Dt} = \partial_t h + u\partial_x h, \quad \ddot{h} = \frac{D\dot{h}}{Dt}.$$

$$\Pi = \frac{h^2}{2} \frac{D[u\partial_x b]}{Dt}, \quad f = h\partial_x b \left(\frac{\ddot{h}}{2} + \frac{D[u\partial_x b]}{Dt} \right).$$

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Reformulation of the SGN equations (1)

Elliptic operator

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ (I + \mathcal{T}[h, b]) (\partial_t hu + \partial_x(hu^2)) + gh\partial_x\xi + h\mathcal{Q}[h, u, b] = 0. \end{cases}$$

$$\mathcal{T}[h, b]w = -\frac{h^2}{3}\partial_x^2 w - h\partial_x h\partial_x w + f(b)w.$$

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▷ P. Bonneton *et al.*, *A splitting approach for the fully nonlinear and weakly dispersive Green-Naghdi model*, 2011.

▷ D. Lannes, F. Marche, *A new class of fully nonlinear and weakly dispersive Green-Naghdi models for efficient 2D simulations*, 2015.

Reformulation of the SGN equations (1)

Elliptic operator

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ (I + \mathcal{T}[h, b]) (\partial_t hu + \partial_x(hu^2)) + gh\partial_x\xi + h\mathcal{Q}[h, u, b] = 0. \end{cases}$$

$$\mathcal{T}[h, b]w = -\frac{h^2}{3}\partial_x^2 w - h\partial_x h\partial_x w + f(b)w.$$

► We set :

$$\mathcal{D} = gh\partial_x\xi - (I + \mathcal{T}[h, b])^{-1} (gh\partial_x\xi + h\mathcal{Q}).$$

► Shallow Water with source term :

$$\begin{cases} \partial_t h + \partial(hu) = 0, \\ \partial_t hu + \partial_x(hu^2) + gh\partial_x\xi = \mathcal{D}. \end{cases}$$

► P. Bonneton et al., *A splitting approach for the fully nonlinear and weakly dispersive Green-Naghdi model*, 2011.

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Reformulation of the SGN equations (2)

Hyperbolic problem with constraint

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t hu + \partial_x\left(hu^2 + \frac{1}{2}gh^2 + \frac{1}{3}h^2\ddot{h}\right) = 0. \end{cases}$$

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► We set $p = h\ddot{h}$.

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► We set $p = h\ddot{h}$.

$$\partial_t hw + \partial_x(huw) = p,$$

where $w = -h\partial_x u \rightsquigarrow$ **constraint.**

► E.D. Fernandez-Nieto, M. Parisot, Y. Penel, J. Sainte-Marie, *A hierarchy of dispersive layer-averaged approximations of Euler equations for free surface flows*, 2018.

► C. Escalante, T. Morales de Luna, M.J. Castro, *Non-hydrostatic pressure shallow flows : GPU implementation using finite volume and finite difference scheme*, 2018.

► S. Noelle, M. Parisot, T. Tscherpel, *A class of boundary conditions for time-discrete Green-Naghdi equations with bathymetry*, 2022.

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► We set $p = h\ddot{h}$.

$$\partial_t hw + \partial_x(huw) = p,$$

where $w = -h\partial_x u \rightsquigarrow$ **constraint**.

► The system is rewritten under the form :

$$\partial_t V + \partial_x A(V) = \Psi(p),$$

with $V = (h, u, w)^T$ and $V \in \mathbb{A}_h := \{ {}^t(h, u, w) \in L^2(\Omega), w = -h\partial_x u \}$

► E.D. Fernandez-Nieto, M. Parisot, Y. Penel, J. Sainte-Marie, *A hierarchy of dispersive layer-averaged approximations of Euler equations for free surface flows*, 2018.

► C. Escalante, T. Morales de Luna, M.J. Castro, *Non-hydrostatic pressure shallow flows : GPU implementation using finite volume and finite difference scheme*, 2018.

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Reformulation of the SGN equations (3)

Hyperbolic problem with constraint

$$\partial_t h + \partial_x hu = 0,$$

$$\partial_t hu + \partial_x \left(hu^2 + \frac{1}{2}gh^2 + \frac{1}{3}hp \right) = 0,$$

$$\partial_t hw + \partial_x(huw) = p,$$

$$w = -h\partial_x u \quad \rightsquigarrow \text{constraint}$$

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Reformulation of the SGN equations (3)

Hyperbolic system with relaxation term

$$\partial_t h + \partial_x hu = 0,$$

$$\partial_t hu + \partial_x \left(hu^2 + \frac{1}{2}gh^2 + \frac{1}{3}hp \right) = 0,$$

$$\partial_t hw + \partial_x(huw) = p,$$

$$\partial_t hp + \partial_x(hup) = -\lambda(w + h\partial_x u), \quad \lambda \gg 1.$$

-
- ▷ **N. Favrie, S. Gavriluk**, *A rapid numerical method for solving Serre–Green–Naghdi equations describing long free surface gravity waves*, 2017.
 - ▷ **C. Escalante et al.**, *On high order ADER Discontinuous Galerkin schemes for first order hyperbolic reformulations of nonlinear dispersive systems*, 2019.
 - ▷ **G. Richard**, *An extension of the Boussinesq-type models to weakly compressible flows*, 2021.
 - ▷ **J.L. Guermond et al.**, *Robust explicit relaxation technique for solving the Green-Naghdi equations*, 2019.

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The *Leucothéa* model (LcT) - G.L. Richard, 2021

1d version, flat bottom

$$(LcT) \quad \left\{ \begin{array}{l} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + \frac{1}{2}gh^2 + hP) = 0, \\ \partial_t(hW) + \partial_x(huW) = \frac{3}{2}P, \\ \partial_t(hP) + \partial_x(huP) = -a^2(2W + h\partial_x u). \end{array} \right.$$

a : acoustic speed

W : depth-averaged vertical speed

P : depth-averaged non-hydrostatic pressure

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▷ G. Richard, *An extension of the Boussinesq-type models to weakly compressible flows*, 2021.

Model features

► Hyperbolicity

$$\partial_t V + A(V)\partial_x V = S(V),$$

$$\lambda_{1,2} = u \quad , \quad \lambda_{3,4} = u \pm \sqrt{gh + P + a^2}.$$

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$$\partial_t V + A(V)\partial_x V = S(V),$$

$$\lambda_{1,2} = u \quad , \quad \lambda_{3,4} = u \pm \sqrt{gh + P + a^2}.$$

► Energy

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 + hP \right) u \right) = 0,$$

$$E = \frac{1}{2}hu^2 + \frac{1}{2}gh^2 + \frac{2}{3}hW^2 + \frac{1}{2a^2}hP^2.$$

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$$\partial_t V + A(V) \partial_x V = S(V),$$

$$\lambda_{1,2} = u \quad , \quad \lambda_{3,4} = u \pm \sqrt{gh + P + a^2}.$$

► Energy

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2} gh^2 + hP \right) u \right) = 0,$$

$$E = \frac{1}{2} hu^2 + \frac{1}{2} gh^2 + \frac{2}{3} hW^2 + \frac{1}{2a^2} hP^2.$$

► Dispersion relation

$$\frac{h_0^2}{3a^2} \omega^4 - \omega^2 \left(1 + \frac{k^2 h_0^2}{3} \left(1 + \frac{gh_0}{a^2} \right) \right) + k^2 gh_0 = 0.$$

▷ $a \rightarrow +\infty$: dispersion relation :

$$\omega_{GN}^2(k) = gk^2 h_0 \left(\frac{1}{1 + (kh_0)^2/3} \right).$$

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Numerical scheme

Hyperbolic / acoustic splitting

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + \frac{1}{2}gh^2 + hP) = 0, \\ \partial_t(hW) + \partial_x(huW) = \frac{3}{2}P, \\ \partial_t(hP) + \partial_x(huP) = -a^2(2W + h\partial_x u). \end{cases}$$

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$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) u \right) = 0.$$

$$\partial_t E + \partial_x(hPu) = 0.$$

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Hyperbolic step

Shallow Water with passive transport

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + \frac{1}{2}gh^2) = 0, \\ \partial_t(hW) + \partial_x(huW) = 0, \\ \partial_t(hP) + \partial_x(huP) = 0. \end{cases}$$

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) u \right) = 0.$$

Discrete counterpart of the energy equation :

$$\frac{E_K^{n+1} - E_K^n}{\Delta t} + \frac{G_{K+1/2}^{SW} - G_{K-1/2}^{SW}}{\Delta x} \leq 0.$$
$$E_K^{n+1} \leq E_K^n - \frac{\Delta t}{\Delta x} \left(G_{K+1/2}^{SW} - G_{K-1/2}^{SW} \right).$$

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$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) u \right) = 0.$$

Discrete counterpart of the energy equation :

$$\frac{E_K^{n+1} - E_K^n}{\Delta t} + \frac{G_{K+1/2}^{SW} - G_{K-1/2}^{SW}}{\Delta x} \leq 0.$$
$$E_K^{n+1} \leq E_K^n - \frac{\Delta t}{\Delta x} \left(G_{K+1/2}^{SW} - G_{K-1/2}^{SW} \right).$$

Requirements :

- ▶ **Explicit** methods.
- ▶ Inclusion of **topography** terms.
- ▶ **Minimize** diffusion.
- ▶ Extension in 2d on **unstructured** meshes.

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The CPR approach - Continuous frame

Back to the Shallow Water equations

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2) + h\partial_x\phi = 0, \end{cases} \quad \phi = g(h + b).$$

► Energy equation : $E = \frac{1}{2}hu^2 + \frac{1}{2}gh^2 + gb.$

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) u \right) = 0.$$

-
- **N. Grenier et al.**, *An accurate low-Mach scheme for a compressible two-fluid model applied to free-surface flows*, 2013.
 - **M. Parisot, J.P. Vila**, *Centered-potential regularization for the advection upstream splitting method*, 2016.
 - **F. Couderc et al.**, *An explicit asymptotic preserving low Froude scheme for the multilayer shallow water model with density stratification*, 2017.

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Back to the Shallow Water equations

$$\begin{cases} \partial_t h + \partial_x(h(u - \delta u)) = 0, \\ \partial_t(hu) + \partial_x(hu(u - \delta u)) + h\partial_x\phi = 0, \end{cases} \quad \phi = g(h + b).$$

► Energy equation : $E = \frac{1}{2}hu^2 + \frac{1}{2}gh^2 + gb.$

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) (u - \delta u) \right) = -h\partial_x\phi\delta u.$$

-
- N. Grenier *et al.*, *An accurate low-Mach scheme for a compressible two-fluid model applied to free-surface flows*, 2013.
 - M. Parisot, J.P. Vila, *Centered-potential regularization for the advection upstream splitting method*, 2016.
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- Energy equation : $E = \frac{1}{2}hu^2 + \frac{1}{2}gh^2 + gb.$

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) (u - \delta u) \right) = \underbrace{-h\partial_x\phi\delta u}_{-\gamma(\partial_x\phi)^2}.$$

- Energy dissipation :

$$u^* = u - \delta u \quad , \quad \delta u = \gamma\partial_x\phi.$$

-
- **N. Grenier et al.**, *An accurate low-Mach cheme for a compressible two-fluid model applied to free-surface flows*, 2013.
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Continuous level

$$\begin{cases} \partial_t h + \partial_x(h(u - \delta u)) = 0, \\ \partial_t(hu) + \partial_x(hu(u - \delta u)) + h\partial_x\phi = 0, \end{cases} \quad \phi = g(h + b).$$

Energy

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) (u - \delta u) \right) = \underbrace{-h\partial_x\phi\delta u}_{-\gamma(\partial_x\phi)^2}.$$

Discrete level ($u^* = \bar{u} - \gamma\delta\phi$)

$$\begin{aligned} h_K^{n+1} &= h_K^n - \Delta t \partial_K(hu^*) \\ (hu)_K^{n+1} &= (hu)_K^n - \Delta t \partial_K^{up}(u, hu^*) - \Delta t h_K^{n+1} \partial_K^c \phi. \end{aligned}$$

Energy

$$\frac{E_K^{n+1} - E_K^n}{\Delta t} + \frac{1}{\Delta x} (\mathcal{G}_{K+1/2} - \mathcal{G}_{K-1/2}) \leq (1 - \gamma) \left(\frac{\Delta t}{\Delta x} \right)^2 \bar{h} (\delta_K \phi)^2$$

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Numerical scheme

Hyperbolic / acoustic splitting

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + \frac{1}{2}gh^2 + hP) = 0, \\ \partial_t(hW) + \partial_x(huW) = \frac{3}{2}P, \\ \partial_t(hP) + \partial_x(huP) = -a^2(2W + h\partial_x u). \end{cases}$$

$$\begin{cases} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + \frac{1}{2}gh^2) = 0, \\ \partial_t(hW) + \partial_x(huW) = 0, \\ \partial_t(hP) + \partial_x(huP) = 0. \end{cases} \quad \begin{cases} \partial_t h = 0, \\ \partial_t(hu) = -\partial_x(hP), \\ \partial_t(hW) = \frac{3}{2}P, \\ \partial_t(hP) = -a^2(2W + h\partial_x u). \end{cases}$$

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 \right) u \right) = 0.$$

$$\partial_t E + \partial_x(hPu) = 0.$$

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Including dispersion

Acoustic system (flat bottom)

$$\begin{cases} \partial_t h = 0, \\ \partial_t(hu) = -\partial_x(hP), \\ \partial_t(hW) = \frac{3}{2}P, \\ \partial_t(hP) = -a^2(2W + h\partial_x u). \end{cases}$$

- ▶ Energy equation :

$$\partial_t E + \partial_x(hPu) = 0.$$

- ▶ Discrete counterpart :

$$E_K^{n+1} \leq E_K^n - \frac{\Delta t}{\Delta x} \left(G_{K+1/2}^{ac} - G_{K-1/2}^{ac} \right).$$

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Acoustic step (1)

Reformulation

$$\left\{ \begin{array}{l} \partial_t h = 0, \\ \partial_t(hu) = -\partial_x(hP), \\ \partial_t(hW) = \frac{3}{2}P, \\ \partial_t(hP) = -a^2(2W + h\partial_x u). \end{array} \right. \Leftrightarrow \left\{ \begin{array}{l} \partial_t h = 0, \\ \partial_t u = -\frac{1}{h}\partial_x(hP), \\ \partial_t W = \frac{3}{2}\frac{P}{h}, \\ \partial_t P = -a^2\left(2\frac{W}{h} + \partial_x u\right). \end{array} \right.$$

Numerical scheme

$$\left\{ \begin{array}{l} \frac{u_K^{n+1} - u_K^n}{\Delta t} = -\frac{1}{h_K}\partial_K^c(hP^{n+1}), \\ \frac{W_K^{n+1} - W_K^n}{\Delta t} = \frac{3}{2}\frac{P_K^{n+1}}{h_K}, \\ \frac{P_K^{n+1} - P_K^n}{\Delta t} = -a^2\left(2\frac{W_K^{n+1}}{h_K} + \partial_K^* u\right). \end{array} \right.$$

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Acoustic step (2)

Numerical scheme

$$\left\{ \begin{array}{l} \frac{u_K^{n+1} - u_K^n}{\Delta t} = -\frac{1}{h_K} \partial_K^c (h P^{n+1}), \\ \frac{W_K^{n+1} - W_K^n}{\Delta t} = \frac{3}{2} \frac{P_K^{n+1}}{h_K}, \\ \frac{P_K^{n+1} - P_K^n}{\Delta t} = -a^2 \left(2 \frac{W_K^{n+1}}{h_K} + \partial_K^* u \right). \end{array} \right.$$

$$\partial_K^* u = \frac{1}{\Delta x} (u_{K+1/2}^* - u_{K-1/2}^*), \quad u_{K+1/2}^* = \bar{u}_{K+1/2} - \beta \frac{\Delta t}{\Delta x} [hP]_{K+1/2}^n.$$

- ▶ Step 1 : **Explicit** resolution of W and P .
- ▶ Step 2 : Evolution of u .

Stability under the CFL condition : $\frac{\Delta t}{\Delta x} a \leq 1/2$.

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Improvement of dispersive properties

Equations SGN

$$\partial_t h + \partial_x hu = 0,$$

$$\left(1 + \underbrace{\mathcal{T}[h, z]}_{\mathcal{O}(\mu)}\right) (\partial_t hu + \partial_x(hu^2)) + gh\partial_x \xi + \underbrace{hQ}_{\mathcal{O}(\mu)} = 0.$$

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Improvement of dispersive properties

Equations SGN

$$\partial_t h + \partial_x hu = 0,$$

$$\left(1 + \underbrace{\mathcal{T}[h, z]}_{\mathcal{O}(\mu)}\right) (\partial_t hu + \partial_x(hu^2)) + gh\partial_x \xi + \underbrace{hQ}_{\mathcal{O}(\mu)} = 0.$$

► $\partial_t hu = -\partial_x(hu^2) - gh\partial_x \xi + \mathcal{O}(\mu).$

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Equations SGN

$$\partial_t h + \partial_x hu = 0,$$

$$\left(1 + \underbrace{\mathcal{T}[h, z]}_{\mathcal{O}(\mu)}\right) (\partial_t hu + \partial_x(hu^2)) + gh\partial_x\xi + \underbrace{hQ}_{\mathcal{O}(\mu)} = 0.$$

► $\partial_t hu = -\partial_x(hu^2) - gh\partial_x\xi + \mathcal{O}(\mu).$

► Introduction of the parameter α

$$\partial_t hu = \alpha\partial_t hu + (1 - \alpha)(-\partial_x(hu^2) - gh\partial_x\xi) + \mathcal{O}(\mu).$$

► P. Bonneton et al., *A splitting approach for the fully nonlinear and weakly dispersive Green-Naghdi model*, 2011.

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Improvement of dispersive properties

Equations SGN

$$\partial_t h + \partial_x hu = 0,$$

$$\left(I + \underbrace{\mathcal{T}[h, z]}_{\mathcal{O}(\mu)} \right) (\partial_t hu + \partial_x(hu^2)) + gh\partial_x \xi + \underbrace{hQ}_{\mathcal{O}(\mu)} = 0.$$

► $\partial_t hu = -\partial_x(hu^2) - gh\partial_x \xi + \mathcal{O}(\mu).$

► Introduction of the parameter α

$$\partial_t hu = \alpha \partial_t hu + (1 - \alpha)(-\partial_x(hu^2) - gh\partial_x \xi) + \mathcal{O}(\mu).$$

► Momentum equation

$$\left(I + \alpha \mathcal{T}[h, z] \right) \left(\partial_t hu + \partial_x(hu^2) + \frac{\alpha - 1}{\alpha} gh\partial_x \xi \right) + \frac{1}{\alpha} gh\partial_x \xi + hQ_1 = 0.$$

The LcT model with improved dispersive properties and exact energy conservation

Final system

$$\left\{ \begin{array}{l} \partial_t h + \partial_x(hu) = 0, \\ \partial_t(hu) + \partial_x(hu^2 + \frac{1}{2}gh^2 + hP) = 0, \\ \partial_t(hW) + \partial_x(huW) = \frac{3}{2}P + \frac{\alpha - 1}{2\alpha}gh^{3/2}\partial_x B, \\ \partial_t(hP) + \partial_x(huP) = -a^2(2W + \alpha h\partial_x u), \\ \partial_t(hB) + \partial_x(huB) = \partial_x(2h^{3/2}W). \end{array} \right.$$

Energy equation

$$\partial_t E + \partial_x \left(\left(E + \frac{1}{2}gh^2 + hP + \Pi_B \right) u \right) = 0,$$

$$E = \frac{1}{2}hu^2 + \frac{1}{2}gh^2 + \frac{2}{3\alpha}hW^2 + \frac{1}{2\alpha a^2}hP^2 + \frac{\alpha - 1}{6\alpha^2}ghB^2,$$

$$\Pi_B = -\frac{2}{3} \frac{\alpha - 1}{\alpha^2} gh^{3/2}WB.$$

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Symmetrizable systems

$$S_0(U)\partial_t U + \sum_{i=1}^d S_i(U)\partial_{x_i} U + aL^\delta \cdot U = G(U).$$

- Classical frame : control of the solution in H^s .

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Symmetrizable systems

$$S_0(U)\partial_t U + \sum_{i=1}^d S_i(U)\partial_{x_i} U + aL^\delta \cdot U = G(U).$$

- ▶ Classical frame : control of the solution in H^s .
- ▶ Singular limit problem - three scales : 1, a , δ , ($\delta = \sqrt{\mu}$).

Uniform control of :

$$\mathcal{E}_s(U) = \sum_{j=0}^m \|\partial_t^j U\|_{H^{s-j}}^2 + \sum_{j=m+1}^s (a\delta)^{m-j} \|\partial_t^j U\|_{H^{s-j}}^2.$$

with respect to $0 < 1/a \leq \delta$.

- ▶ **V. Duchêne**, *Rigorous justification of the Favrie–Gavrilyuk approximation to the Serre–Green–Naghdi model*, 2019.

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Objectives : (with K. Msheik and V. Duchêne)

- ▶ Application to the 2d LcT model with topography.
- ▶ Relax conditions on the initial data.

$$\tilde{\mathcal{E}}_s(U) = \sum_{i+j=0}^s \alpha_{i,j}^{-2} \|\partial_t^j U\|_{H^i}^2.$$

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Numerical analysis and schemes

		$\partial_x b = 0$	mild slope	full system
1D	(LcT)	✓	✓	✓
	$(LcT)_{\alpha}^{cons}$	✓	✓	✗
2D NS	(LcT)	✓	(✓)	✗
	$(LcT)_{\alpha}^{cons}$	(✓)	(✓)	✗

Work in progress

- ▶ Numerical validations (with F. Couderc).
- ▶ Comparaisons SGN vs LcT (with F. Marche).
- ▶ Justification of the LcT model (with V. Duchêne, K. Msheik).
- ▶ Two-layer extension (with G. Richard, K. Msheik, ...).
- ▶ Wave-breaking (PHD of Y. C. Hung, Chambéry).
- ▶ High order extension (with L. Emerald, D. Le Roux).
- ▶ Multilayer SW (with L. Emerald, P. Noble) .

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2D NS	(LcT)	✓	(✓)	✗
	$(LcT)_{\alpha}^{cons}$	(✓)	(✓)	✗

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