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Dictionary-based model reduction for state estimation

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We consider in [4] the problem of state estimation from m linear measurements, where the state u to recover is an element of the manifold \mathcal{M} of solutions of a parameter-dependent equation. The state is estimated using prior knowledge on \mathcal{M} coming from model order reduction. Variational approaches based on linear approximation, such as [3], yields a recovery error limited by the Kolmogorov m-width of \mathcal{M} . To overcome this issue, piecewise-affine approximations [2] of the manifold have also be considered, that consist in using a library of linear spaces among which one is selected by minimizing some distance to the manifold.

In [4] we propose a state estimation method relying on dictionary-based model reduction, where a space is selected from a library generated by a dictionary of snapshots, using a distance to the manifold. The selection is performed among a set of candidate spaces obtained from the path of a ℓ_1 -regularized least-squares problem. Then, in the framework of parameter-dependent operator equations (or PDEs) with affine parameterization, we provide an efficient offline-online decomposition based on randomized linear algebra [1], that ensures efficient and stable computations while preserving theoretical guarantees.

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